

Boyuan Chen

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EDUCATION

Massachusetts Institute of Technology (MIT), PhD student in EECS 2021 - Present
UC Berkeley, BA Computer Science (EECS Honor Class), Applied Math, Class of 2021, GPA 3.96 2017-2021

Selected Coursework: Deep Unsupervised Learning(A+), Deep Reinforcement Learning(A+), Advanced Robotics(A+), Natural Language Processing(A), Machine Learning(A), Computer Vision(A), AI System(A+), Hardware for Deep Learning(A), Robotics(A+), Real Analysis(A+), Complex Analysis(A+), Algorithms(A), Data Structure(A), Computer Program(A+), Computer Architecture(A), Stochastic Process & Probability(A)

EXPERIENCE

Google DeepMind

Research Intern May 2023 - Aug 2023

- Lead the training of a multi-modal Large Language Model (MLLM) with large scale synthetic data.
- Implemented the entire data synthesis pipeline, Instruction tuning and Visual grounding.

Google X (or X, the Moonshot Factory)

AI resident, machine learning for robotics (with return offer at Google's L4 level but declined) May 2022 - Aug 2022

- Develop machine learning algorithms for sequential decision making in robotics
- Visual grounding for Large Language Model

MIT Computer Science and Artificial Intelligence Laboratory (CSAIL)

Researcher Sep 2021 - present

- Machine learning & robotics advised by Prof. Russ Tedrake and Prof. Vincent Sitzmann

Berkeley Artificial Intelligence Research Lab

Researcher Jan 2019 - Aug 2021

- Computer vision research Prof. Trevor Darrell; Reinforcement learning research with Prof. Pieter Abbeel
- Student researcher on unsupervised learning, 3d vision, visual reinforcement learning and generalizable manipulation.

Robomoc.com, Chongqing Muke Robotics Inc.

Startup Founder Nov 2017 - Mar 2020

- Company providing robotics education solution to K12 education
- Lead the software and hardware development of robot kits that we sell to student participants in robotics competitions

Robomaster at Berkeley (Robotics Team & Club)

Founder, Captain Oct 2018 - 2021

- Lead 20-member robotics team building autonomous shooting robots for ICRA RoboMaster AI Challenge
- Designed and implemented novel methods for data collection, object detection and inference acceleration

Open Source Project Contributor

- Contributor of DL Framework Pytorch, Torchvision; Physics Engine Bullet3; Robotics framework Drake 2018 - 2021

MIT Chess club

- Executive at MIT Chess Club 2021 - present
- Team member of MIT in collegiate chess league

SKILLSET

Language & Tools: Python, C++/C, Java, PyTorch, Tensorflow, Jax, Pax, Flume, OpenCV, MongoDB, TensorRT, ZeroMQ, Qt5

Machine Learning: Deep Reinforcement Learning, Large Language Model, Data synthesis, Generative Models (Diffusion, Flow, GAN, VAE, EBM), Video Prediction, Gaussian Splatting, Variational Inference, Time Series Prediction, Imitation Learning.

PUBLICATION

Spatial VLM: Endowing Vision-Language Models with Spatial Reasoning Capabilities Arxiv 2024

[B. Chen](#), Z. Xu, S. Kirmani, B. Ichter, D. Driess, P. Florence, D. Sadigh, L. Guibas, F. Xia

DittoGym: Learning to Control Soft Shape-Shifting Robots ICLR 2024

S. Huang, [B. Chen](#), H. Xu, V. Sitzmann

Self-Supervised Reinforcement Learning that Transfers using Random Features NeurIPS 2023

[B. Chen](#), C. Zhu, P. Agrawal, K. Zhang, A. Gupta

Open-vocabulary Queryable Scene Representations for Real World Planning ICRA 2023

B. Chen, F. Xia, B. Ichter, K. Rao, K. Gopalakrishnan, M. Ryoo, A. Stone, D. Kappler Reasoning or Reciting? Exploring the Capabilities and Limitations of LLM Through Counterfactual Tasks	NAACL 2024
Z. Wu, L. Qiu, A. Ross, E. Akyürek, B. Chen, B. Wang, N. Kim, J. Andreas, Y. Kim Extraneousness-Aware Imitation Learning	ICRA 2023
R. Zheng, K. Hu, B. Chen, H. Xu. In submission to Neurips 2023 Unsupervised 3d Keypoint Learning for control	ICML 2021
B. Chen, D. Pathak, P. Abbeel. Accepted to ICML 2021. Zero-shot Policy Learning with Spatial Temporal Reward Decomposition on Contingency-aware Observation	ICRA 2020
B. Chen*, H. Xu*, Y. Gao, T. Darrell. Accepted to ICRA 2021 Discovering Diverse Multi-Agent Strategic Behavior via Reward Randomization	ICLR 2021
Z. Tang, C. Yu, B. Chen, H. Xu, X Wang, F. Fang, S. Du, Y. Wang, Y. Wu	

ACADEMIC SERVICE

Reviewer of CVPR, NeurIPS, ICLR, ICRA, IROS, RAL, AAAI	2021-
Teaching Assistant, MIT 6.4210/6.4212 Robotic Manipulation	Sep 2022 – Dec 2022

PERSONAL PROJECTS

Autonomous multi-floor food delivery robot (Control, Planning, Sensing, Vision, ROS)	Sep 2019 - Dec 2019
ICRA Robomaster AI Challenge Autonomous Combat Robot (Vision, Planning, ROS, Control, AI)	Jan 2019 - May 2019
Personal drivable RC robot (CAD, Manufacture, Electronics, Control, Embedded System)	May 2019 - Aug 2019
Autonomous Multi-Terrain Rover (CAD, Manufacture, Electronics, Computer Vision, Planning)	Oct 2017 - Aug 2018
Autonomous Tracking Drone (Computer Vision, Embedded System)	Sep 2016 - Aug 2017

HONOR

Seneff-Zue CS Fellowship	Feb 2021
Winner, Facebook Pytorch Summer Hackathon	Aug 2019
Finalist, ICRA 2019 Robomaster AI Challenge	May 2019
Winner, Record Keeper, UC Berkeley CS 61C Neural Network Inference Optimization Contest	Aug 2018
Winner, CS170 Efficient Algorithms Contest	Oct 2018
2 nd place, Google Puzzlehunt, second fastest prize eligible team out of 800+ teams of Google employees	Jul 2022
Honor degree in EECS, High honor in general scholarship, Dean's List, UC Berkeley	2017-2021